

# Local Tensor Valuations

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(based on joint work with Rolf Schneider)

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## Getting started

We consider maps

$$\Gamma : \mathcal{P}^n \times \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1}) \rightarrow \mathbb{T}^p \quad \text{or} \quad \Gamma : \mathcal{K}^n \times \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1}) \rightarrow \mathbb{T}^p$$

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- (b) **isometry covariant**:
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- (c) **locally defined**:  $\Gamma(K, \eta) = \Gamma(K', \eta)$  whenever  $\eta \in \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1})$  and  $\eta \cap \text{Nor } K = \eta \cap \text{Nor } K'$ .

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- (d) **weakly continuous**: if  $\lim_{i \rightarrow \infty} K_i = K$  then

$$\lim_{i \rightarrow \infty} \int_{\mathbb{R}^n \times \mathbb{S}^{n-1}} f \, d\Gamma(K_i, \cdot) = \int_{\mathbb{R}^n \times \mathbb{S}^{n-1}} f \, d\Gamma(K, \cdot)$$

for all continuous functions  $f : \mathbb{R}^n \times \mathbb{S}^{n-1} \rightarrow \mathbb{R}$ .

# Examples

1. For  $K \in \mathcal{K}^n$  and  $\eta \in \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1})$

$$\phi_k^{r,s}(K, \eta) := c_{n,k}^{r,s} \int_{\eta} x^r u^s \Lambda_k(K, d(x, u))$$

for  $r, s, k \in \mathbb{N}_0$  with  $k \leq n - 1$ .

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2. For  $P \in \mathcal{P}^n$

$$\phi_k^{r,s,j}(P, \eta) := C_{n,k}^{r,s} \sum_{F \in \mathcal{F}_k(P)} Q_{L(F)}^j \int_F \int_{\nu(P,F)} \mathbf{1}_{\eta}(x, u) x^r u^s \mathcal{H}^{n-k-1}(du) \mathcal{H}^k(dx)$$

for  $r, s, j, k \in \mathbb{N}_0$  with  $1 \leq k \leq n - 1$ ;  $\phi_0^{r,s,0} := \phi_0^{r,s}$ .



## A local characterization theorem: polytopes

For  $p \in \mathbb{N}_0$ , let  $T_p(\mathcal{P}^n)$  denote the real vector space of all mappings  $\Gamma : \mathcal{P}^n \times \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1}) \rightarrow \mathbb{T}^p$  with the following properties:

- (a)  $\Gamma(P, \cdot)$  is a  $\mathbb{T}^p$ -valued measure, for each  $P \in \mathcal{P}^n$ ;
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**Theorem 1** A *basis* of  $T_p(\mathcal{P}^n)$  is given by the mappings

$$Q^m \phi_k^{r,s,j},$$

where  $m, r, s, j \in \mathbb{N}_0$  satisfy  $2m + 2j + r + s = p$  and where  $k \in \{0, \dots, n-1\}$ , but  $j = 0$  if  $k \in \{0, n-1\}$ .

## A local characterization theorem: polytopes

For  $p \in \mathbb{N}_0$ , let  $T_p^{(0)}(\mathcal{P}^n)$  denote the real vector space of all mappings  $\Gamma : \mathcal{P}^n \times \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1}) \rightarrow \mathbb{T}^p$  with the following properties:

- (a)  $\Gamma(P, \cdot)$  is a  $\mathbb{T}^p$ -valued measure, for each  $P \in \mathcal{P}^n$ ;
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## General convex bodies

Why did we not define  $\phi_K^{r,s,j}(K, \cdot)$  for  $K \in \mathcal{K}^n$  and  $j \geq 1$ ?

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Why did we not define  $\phi_k^{r,s,j}(K, \cdot)$  for  $K \in \mathcal{K}^n$  and  $j \geq 1$ ?

At least for  $k = n - 1$  we can replace  $Q_{L(F)}^j$  in

$$C_{n,n-1}^{r,s} \sum_{F \in \mathcal{F}_{n-1}(P)} Q_{L(F)}^j \int_F \int_{\nu(P,F)} \mathbf{1}_\eta(x, u) x^r u^s \mathcal{H}^0(du) \mathcal{H}^{n-1}(dx)$$

by

$$Q_{L(F)}^j = (Q - u^2)^j = \sum_{i=0}^j (-1)^i \binom{j}{i} Q^{j-i} i^{2i}$$

so that

$$\phi_{n-1}^{r,s,j} = \sum_{i=0}^j (-1)^i \binom{j}{i} \frac{(s+2i)! \omega_{1+s+2i}}{s! \omega_{1+s}} Q^{j-i} \phi_{n-1}^{r,s+2i}.$$

## Splitting wrt degree of homogeneity

$\Gamma : \mathcal{K}^n \times \mathcal{B}(\mathbb{R}^n \times \mathbb{S}^{n-1}) \rightarrow \mathbb{T}^p$  is homogeneous of degree  $k$  if

$$\Gamma(\lambda K, \lambda \eta) = \lambda^k \Gamma(K, \eta), \quad K \in \mathcal{K}^n, \eta \in \mathcal{B}(\Sigma^n), \lambda > 0,$$

where  $\lambda \eta := \{(\lambda x, u) : (x, u) \in \eta\}$ .

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**Lemma** Let  $p \in \mathbb{N}_0$ . Let  $\Gamma : \mathcal{K}^n \times \mathcal{B}(\Sigma^n) \rightarrow \mathbb{T}^p$  be such that

- (a)  $\Gamma(K, \cdot)$  is a  $\mathbb{T}^p$ -valued measure, for each  $K \in \mathcal{K}^n$ ;
- (b)  $\Gamma$  is translation invariant and rotation covariant;
- (c)  $\Gamma$  is locally defined;
- (d)  $\Gamma$  is weakly continuous.

Then  $\Gamma = \sum_{k=0}^{n-1} \Gamma_k$ , where each  $\Gamma_k$  has properties (a) – (d) and is homogeneous of degree  $k$ .



**Proof.** The restriction  $\Gamma|_{\mathcal{P}^n \times \mathcal{B}(\Sigma^n)}$  has all the properties required to apply the characterization result for polytopes. Hence it is a linear combination of  $Q^m \phi_k^{0,s,j}$  so that

$$\Gamma|_{\mathcal{P}^n \times \mathcal{B}(\Sigma^n)} = \sum_{k=0}^{n-1} \Gamma_k$$

with  $\Gamma_k : \mathcal{P}^n \times \mathcal{B}(\Sigma^n) \rightarrow \mathbb{T}^p$ . This shows that

$$\Gamma(\lambda P, \lambda \eta) = \sum_{k=0}^{n-1} \lambda^k \Gamma_k(P, \eta), \quad P \in \mathcal{P}^n, \eta \in \mathcal{B}(\Sigma^n), \lambda > 0.$$

This relation can be inverted coordinate-wise, i.e.

$$\Gamma_k(P, \eta) = \sum_{r=1}^n b_{kr} \Gamma(rP, r\eta), \quad k = 0, \dots, n-1,$$

and used to define  $\Gamma_k$  for general convex bodies.

## Weakly continuous extension for $j = 1$

The normal bundle of  $K \in \mathcal{K}^n$  is the  $(n - 1)$ -rectifiable set

$$\text{Nor } K := \{(x, u) \in \partial K \times \mathbb{S}^{n-1} : \langle x, u \rangle = h(K, u)\}.$$

For  $\mathcal{H}^{n-1}$  almost all  $(x, u) \in \text{Nor } K$ , the tangent space  $\text{Tan}^{n-1}(K, (x, u))$  is an  $(n - 1)$ -dimensional linear subspace spanned by  $a_1(x, u), \dots, a_{n-1}(x, u)$ , where

$$a_i(x, u) := \left( \frac{1}{\sqrt{1 + k_i(x, u)^2}} b_i(x, u), \frac{k_i(x, u)}{\sqrt{1 + k_i(x, u)^2}} b_i(x, u) \right),$$

$b_1(x, u), \dots, b_{n-1}(x, u)$  is a suitably oriented ONB of  $u^\perp$ , and  $k_i(x, u) \in [0, \infty]$ .

We define an  $(n - 1)$ -vector

$$a_K(x, u) := a_1(x, u) \wedge \dots \wedge a_{n-1}(x, u),$$

which orients  $\text{Tan}^{n-1}(K, (x, u))$  and then an  $(n - 1)$ -dimensional current in  $\mathbb{R}^{2n}$  by

$$T_K := \left( \mathcal{H}^{n-1} \llcorner \text{Nor } K \right) \wedge a_K,$$

the normal cycle of  $K$ . More explicitly,

$$T_K(\varphi) = \int_{\text{Nor } K} \langle a_K(x, u), \varphi(x, u) \rangle \mathcal{H}^{n-1}(d(x, u)),$$

for all  $\mathcal{H}^{n-1} \llcorner \text{Nor } K$ -integrable functions  $\varphi : \mathbb{R}^{2n} \rightarrow \wedge^{n-1} \mathbb{R}^{2n}$ .

## Lipschitz–Killing forms

Differential forms  $\varphi_k : \mathbb{R}^{2n} \rightarrow \bigwedge^{n-1} \mathbb{R}^{2n}$ ,  $k \in \{0, \dots, n-1\}$ , of degree  $n-1$  on  $\mathbb{R}^{2n}$  are defined by

$$\varphi_k(x, u)(\xi_1, \dots, \xi_{n-1}) := \frac{1}{k!(n-1-k)!\omega_{n-k}} \sum_{\sigma \in S(n-1)} \operatorname{sgn}(\sigma) \left\langle \bigwedge_{i=1}^k \Pi_1 \xi_{\sigma(i)} \wedge \bigwedge_{i=k+1}^{n-1} \Pi_2 \xi_{\sigma(i)} \wedge u, \Omega_n \right\rangle,$$

where  $\xi_1, \dots, \xi_{n-1} \in \mathbb{R}^{2n} = \mathbb{R}^n \times \mathbb{R}^n$ .

A straightforward calculation shows that

$$\langle a_K(x, u), \varphi_k(x, u) \rangle = \frac{1}{\omega_{n-k}} \sum_{|I|=n-1-k} \frac{\prod_{i \in I} k_i(x, u)}{\prod_{i=1}^{n-1} \sqrt{1 + k_i(x, u)^2}}$$

for  $\mathcal{H}^{n-1}$  almost all  $(x, u) \in \operatorname{Nor} K$ , hence

$$T_K(\mathbf{1}_\eta \varphi_k) = \Lambda_k(K, \eta).$$

## Current representation of $\varphi_k^{r,s,1}$

Let  $n \geq 3$ ,  $k \in \{1, \dots, n-2\}$  and  $r, s \in \mathbb{N}_0$ . Let  $(x, u) \in \mathbb{R}^{2n}$  and  $\mathbf{v} = (v_1, \dots, v_{r+s+2}) \in (\mathbb{R}^n)^{r+s+2}$ . For  $\xi_1, \dots, \xi_{n-1} \in \mathbb{R}^{2n}$ , define

$$\begin{aligned} \tilde{\varphi}_k^{r,s}(x, u; \mathbf{v}; \xi_1, \dots, \xi_{n-1}) &:= \frac{C_{n,k}^{r,s}}{(k-1)!(n-1-k)!} x^r(v_1, \dots, v_r) u^s(v_{r+1}, \dots, v_{r+s}) \\ &\times \sum_{\sigma \in S(n-1)} \operatorname{sgn}(\sigma) \langle v_{r+s+1}, \Pi_1 \xi_{\sigma(1)} \rangle \left\langle v_{r+s+2} \wedge \bigwedge_{i=2}^k \Pi_1 \xi_{\sigma(i)} \wedge \bigwedge_{i=k+1}^{n-1} \Pi_2 \xi_{\sigma(i)} \wedge u, \Omega_n \right\rangle. \end{aligned}$$

For fixed  $x, u, \mathbf{v}$ , the map

$$\tilde{\varphi}_k^{r,s}(x, u; \mathbf{v}; \cdot) : (\mathbb{R}^{2n})^{n-1} \rightarrow \mathbb{R}$$

is multilinear and alternating, hence an element of  $\bigwedge^{n-1} \mathbb{R}^{2n}$ .

# Current representation of $\varphi_k^{r,s,1}$

Symmetrization gives

$$\begin{aligned} & \varphi_k^{r,s}(x, u; \mathbf{v}; \xi_1, \dots, \xi_{n-1}) \\ & := \frac{1}{(r+s+2)!} \sum_{\tau \in S(r+s+2)} \tilde{\varphi}_k^{r,s}(x, u; v_{\tau(1)}, \dots, v_{\tau(r+s+2)}; \xi_1, \dots, \xi_{n-1}). \end{aligned}$$

Then

$$\varphi_k^{r,s}(x, u) : (\xi_1, \dots, \xi_{n-1}) \mapsto \varphi_k^{r,s}(x, u; \cdot; \xi_1, \dots, \xi_{n-1})$$

is an  $(n-1)$ -covector of  $\mathbb{T}^{r+s+2}$ , i.e.  $\in \bigwedge^{n-1}(\mathbb{R}^{2n}, \mathbb{T}^{r+s+2})$ .

The map

$$\varphi_k^{r,s} : \mathbb{R}^{2n} \rightarrow \bigwedge^{n-1}(\mathbb{R}^{2n}, \mathbb{T}^{r+s+2}), \quad (x, u) \mapsto \varphi_k^{r,s}(x, u),$$

is a differential form of degree  $n-1$  on  $\mathbb{R}^{2n}$  with coefficients in  $\mathbb{T}^{r+s+2}$ , i.e.  $\in \mathcal{E}^{n-1}(\mathbb{R}^{2n}, \mathbb{T}^{r+s+2}) := \mathcal{E}(\mathbb{R}^{2n}, \bigwedge^{n-1}(\mathbb{R}^{2n}, \mathbb{T}^{r+s+2}))$ .

# Properties

For  $(x, u) \in \mathbb{R}^{2n}$ ,  $\mathbf{a} \in \bigwedge_{n-1} \mathbb{R}^{2n}$ ,  $\vartheta \in O(n)$ :

- ▶  $\langle \mathbf{a}, \varphi_k^{r,s}(x, u) \rangle \in \mathbb{T}^{r+s+2}$ ,
- ▶  $\langle \vartheta \mathbf{a}, \varphi_k^{r,s}(\vartheta x, \vartheta u) \rangle = \vartheta \langle \mathbf{a}, \varphi_k^{r,s}(x, u) \rangle$ .

where  $\vartheta \xi := (\vartheta p, \vartheta q)$  for  $\xi = (p, q) \in \mathbb{R}^n \times \mathbb{R}^n = \mathbb{R}^{2n}$ .

The following lemma justifies these definitions.

**Lemma.** *If  $P \in \mathcal{P}^n$  and  $\eta \in \mathcal{B}(\Sigma^n)$ , then*

$$T_P(\mathbf{1}_\eta \varphi_k^{r,s}) = \phi_k^{r,s,1}(P, \eta).$$

**Proof** For  $P \in \mathcal{P}^n$  and  $\eta \in \mathcal{B}(\Sigma^n)$ , we show that

$$\begin{aligned}
 T_P(\mathbf{1}_{\eta} \tilde{\varphi}_k^{r,s}(\cdot; \mathbf{v}; \cdot)) &= C_{n,k}^{r,s} \sum_{F \in \mathcal{F}_k(P)} Q_{L(F)}(v_{r+s+1}, v_{r+s+2}) \\
 &\times \int_{\eta \cap (F \times \nu(P,F))} x^r(v_1, \dots, v_r) u^s(v_{r+1}, \dots, v_{r+s}) \mathcal{H}^{n-1}(d(x, u)),
 \end{aligned}$$



**Proof** For  $P \in \mathcal{P}^n$  and  $\eta \in \mathcal{B}(\Sigma^n)$ , we show that

$$T_P(\mathbf{1}_{\eta} \tilde{\varphi}_k^{r,s}(\cdot; \mathbf{v}; \cdot)) = C_{n,k}^{r,s} \sum_{F \in \mathcal{F}_k(P)} Q_{L(F)}(v_{r+s+1}, v_{r+s+2}) \\ \times \int_{\eta \cap (F \times \nu(P,F))} x^r(v_1, \dots, v_r) u^s(v_{r+1}, \dots, v_{r+s}) \mathcal{H}^{n-1}(d(x, u)),$$

For this, we start from the disjoint decomposition

$$\eta \cap \text{Nor } P = \bigcup_{j=0}^{n-1} \bigcup_{F \in \mathcal{F}_j(P)} \eta \cap (\text{relint } F \times \nu(P, F))$$

and use information about  $k_j(x, u) \in \{0, \infty\}$  available for polytopes, when  $(x, u) \in F \times \nu(P, F)$  for a  $j$ -face  $F$  of  $P$ : exactly  $j$  of the  $k_j(x, u)$  are zero.

## Lemma

- (a) For  $K \in \mathcal{K}^n$ ,  $T_K$  is a cycle.
- (b) The map  $K \mapsto T_K$  is a valuation on  $\mathcal{K}^n$ .
- (c) If  $K_i, K \in \mathcal{K}^n$ ,  $i \in \mathbb{N}$ , and  $K_i \rightarrow K$  in the Hausdorff metric, as  $i \rightarrow \infty$ , then  $T_{K_i}(\varphi) \rightarrow T_K(\varphi)$  for all differential forms  $\varphi$  of degree  $n - 1$  on  $\mathbb{R}^{2n}$ .

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**Theorem** The map  $\mathcal{K}^n \times \mathcal{B}(\Sigma^n) \rightarrow \mathbb{T}^{r+s+2}$  defined by  $(K, \eta) \mapsto T_K(\mathbf{1}_\eta \varphi_K^{r,s})$ , satisfies the properties (a) – (d). Hence

$$\phi_K^{r,s,1}(K, \eta) := T_K(\mathbf{1}_\eta \varphi_K^{r,s})$$

defines a weakly continuous extension of the functional first introduced for polytopes.

## Remarks



$$\phi_k^{0,s,1}(P, \Sigma^n) = Q\phi_k^{0,s}(P) - 2\pi(s+2)\phi_k^{0,s+2}(P).$$

▶ More involved relations are available for  $\phi_k^{r,s,1}$ .

▶ We have

$$\phi_k^{r,s,1}(K, \eta) = C_{n,k}^{r,s} \int_{\eta \cap \text{Nor } K} x^r u^s \sum_{i=1}^{n-1} b_i(x, u)^2 \sum_{\substack{|I|=n-1-k \\ i \notin I}} \frac{\prod_{j \in I} k_j(x, u)}{\mathbb{K}(x, u)} \mathcal{H}^{n-1}(d(x, u)).$$

This simplifies for  $k = 1, n - 2$ . If  $n = 3$ , for instance,

$$\phi_1^{r,s,1}(K, \eta) = C_{3,1}^{r,s} \int_{\eta \cap \text{Nor } K} x^r u^s \frac{k_1(x, u)b_2(x, u)^2 + k_2(x, u)b_1(x, u)^2}{\mathbb{K}(x, u)} \mathcal{H}^2(d(x, u)).$$

If  $K$  is smooth, this simplifies further.

## The general classification result

**Theorem** For  $p \in \mathbb{N}_0$ , let  $T_p(\mathcal{K}^n)$  denote the real vector space of all mappings  $\Gamma : \mathcal{K}^n \times \mathcal{B}(\Sigma^n) \rightarrow \mathbb{T}^p$  with the following properties.

- (a)  $\Gamma(K, \cdot)$  is a  $\mathbb{T}^p$ -valued measure, for each  $K \in \mathcal{K}^n$ ;
- (b)  $\Gamma$  is isometry covariant;
- (c)  $\Gamma$  is locally defined;
- (d)  $\Gamma$  is weakly continuous.

Then a basis of  $T_p(\mathcal{K}^n)$  is given by the mappings  $Q^m \phi_k^{r,s,j}$ , where  $m, r, s \in \mathbb{N}_0$  and  $j \in \{0, 1\}$  satisfy  $2m + 2j + r + s = p$  and where  $k \in \{0, \dots, n-1\}$ , but  $j = 0$  if  $k \in \{0, n-1\}$ .

## The general classification result

The preceding theorem is essentially equivalent to (follows from) the next theorem.

**Theorem** *Let  $p \in \mathbb{N}_0$ . Let  $\Gamma : \mathcal{K}^n \times \mathcal{B}(\Sigma^n) \rightarrow \mathbb{T}^p$  be a mapping with the following properties.*

- (a)  $\Gamma(K, \cdot)$  is a  $\mathbb{T}^p$ -valued measure, for each  $K \in \mathcal{K}^n$ ;
- (b)  $\Gamma$  is translation invariant and rotation covariant;
- (c)  $\Gamma$  is locally defined;
- (d)  $\Gamma$  is weakly continuous.

*Then  $\Gamma$  is a linear combination, with constant coefficients, of the mappings  $Q^m \phi_k^{0,s,j}$ , where  $m, s \in \mathbb{N}_0$  and  $j \in \{0, 1\}$  satisfy  $2m + 2j + s = p$  and where  $k \in \{0, \dots, n-1\}$ , but  $j = 0$  if  $k \in \{0, n-1\}$ .*

# Ideas of Proof

- ▶ Reduction to fixed degree of homogeneity  
 $k \in \{1, \dots, n-2\}$  and  $n \geq 3$ .
- ▶ On polytopes  $P$  the mapping  $\Gamma$  is of the form

$$\Gamma(P, \cdot) = \sum_{\substack{m, j, s \geq 0 \\ 2m+2j+s=p}} c_{mjs} Q^m \phi_k^{0,s,j}(P, \cdot)$$

with constants  $c_{mjs}$ .  $\Gamma$  and the mappings  $\phi_k^{0,s,0}$  and  $\phi_k^{0,s,1}$  are weakly continuous. The mapping  $\Gamma'$  defined by

$$\Gamma' := \Gamma - \sum_{\substack{m, j, s \geq 0, j \leq 1 \\ 2m+2j+s=p}} c_{mjs} Q^m \phi_k^{0,s,j}$$

satisfies (a) – (d), on polytopes  $P$  it is of the form

$$\Gamma'(P, \cdot) = \sum_{\substack{m, s \geq 0, j \geq 2 \\ 2m+2j+s=p}} c_{mjs} Q^m \phi_k^{0,s,j}(P, \cdot).$$

**Show that the constants  $c_{mjs}$  with  $j \geq 2$  are zero.**

## How to show that $c_{mjs} = 0$ for $j \geq 2$ .

- ▶ Let  $K_h$  be a cap of height  $h$  cut off from a paraboloid of revolution with axis  $\mathbb{R}e_n$ .



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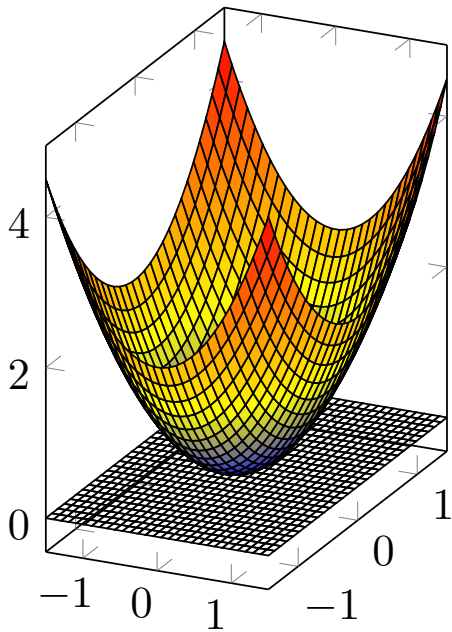
- ▶ Let  $K_h$  be a cap of height  $h$  cut off from a paraboloid of revolution with axis  $\mathbb{R}e_n$ .
- ▶ Clearly,  $K_h$  has plenty of rotational symmetries.
- ▶ Approximate  $K_h$  by a sequence of inscribed polytopes with limited symmetries:
  - ▶ choose a cubical grid of width  $2t$ ,  $t > 0$ , in  $\mathbb{R}^{n-1}$  and lift its vertices to the paraboloid;
  - ▶ let  $P_{t,h}$  be the convex hull of these lifted points;
  - ▶ note that  $P_{t,h} \rightarrow K_h$  as  $t \rightarrow 0+$ .

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- ▶ The faces of  $P_t$  can be described explicitly.  
The symmetries of  $P_t$  can be controlled.
- ▶ We show that the covariance properties of  $\Gamma'(P_{t,h}, \cdot)$  are restricted so strongly that this can be extended to the limiting case. This finally leads to a contradiction with the covariance properties of  $\Gamma'(K_h, \cdot)$  if  $\Gamma' \neq 0$ .



The remaining part of the proof requires a combination of (elementary) algebraic and geometric considerations as well as approximation arguments. We write again  $\Gamma$  instead of  $\Gamma'$  and

$$\Gamma(K, f) := \int_{\Sigma^n} f(u) \Gamma(K, d(x, u))$$

for  $K \in \mathcal{K}^n$  and a continuous real function  $f$  on  $\mathbb{S}^{n-1}$ . For a polytope  $P \in \mathcal{P}^n$ , we define

$$W_k(P, f) := \sum_{F \in \mathcal{F}_k(P)} \mathcal{H}^k(F) \int_{\nu(P, F)} f d\mathcal{H}^{n-k-1}.$$

**Lemma** Let  $s_0$  be the smallest number  $s$  for which  $c_{mjs} \neq 0$  for some  $m, j$ , set  $q := (p - s_0)/2$  and  $c_j := ((2q)!s_0!/p!)c_{(q-j)js_0}C_{n,k}^{0,s_0}$ . Let  $d$  be the largest  $j \in \{2, \dots, q\}$  for which  $c_j \neq 0$ . Let  $\omega \in \mathcal{B}(\mathbb{S}^{n-1})$  and  $0 < \varepsilon < 1$  be such that  $\omega$  is  $\varepsilon$ -close to  $-e_n$ . Let  $f$  be a nonnegative, continuous real function on  $\mathbb{S}^{n-1}$  with support in  $\omega$ . For  $P \in \mathcal{P}^n$ , define

$$\Delta(P, f) := \sum_{j=2}^d c_j Q^{q-j} \sum_{F \in \mathcal{F}_k(P)} Q_{L(F)}^j \mathcal{H}^k(F) \int_{\nu(P,F)} f d\mathcal{H}^{n-k-1} \in \mathbb{T}^{2q}.$$

Let  $E' := \underbrace{(a, \dots, a)}_{2q}$  with  $a \in \mathbb{R}^{n-1}$ ,  $\|a\| = 1$  and

$$E := (b_1, \dots, b_p) := \underbrace{(a, \dots, a)}_{2q}, \underbrace{(-e_n, \dots, -e_n)}_{s_0}.$$

Then

$$|\Gamma(P, f)(E) - \Delta(P, f)(E')| \leq C_3 W_k(P, f)\varepsilon$$

with a constant  $C_3$  depending only on  $\Gamma$ .

We apply this approximation to the polytopes  $P_{t,h}$  to get

$$\begin{aligned}
 & \Gamma(P_{h,t}, f)(E) \\
 &= \sum_{j=2}^d c_j \sum_{i=1}^{b(n,k)} \sum_{F \in \mathcal{F}_{k,h}^i(P_{h,t})} (Q^{q-j} Q_{L_i}^j)(E') \mathcal{H}^k(F) \int_{\nu(P_{h,t}, F)} f \, d\mathcal{H}^{n-k-1} + R_5(E) \\
 &= b(n, k)^{-1} W_k(P_{h,t}, f) \left( \sum_{j=2}^d c_j Q^{q-j} \sum_{i=1}^{b(n,k)} Q_{L_i}^j \right) (E') + R_5(E)
 \end{aligned}$$

with

$$|R_5(E)| \leq C_5 W_k(P_{h,t}, f) \varepsilon,$$

where  $C_5$  depends only on  $\Gamma$ .

**This approximation is crucial for the next lemma.**



**Lemma** *Let  $n \geq 4$ . Under the assumptions made above, there exist a convex body  $K \in \mathcal{K}^n$ , a continuous function  $f$  on  $\mathbb{S}^{n-1}$ , a  $p$ -tuple  $E$ , and a rotation  $\vartheta \in O(n)$  such that  $K$  and  $f$  are invariant under  $\vartheta$ , but  $\Gamma(K, f)(\vartheta E) \neq \Gamma(K, f)(E)$ .*

The proof of this lemma involves the study of the polynomials

$$\sum_{j=2}^d c_j (x_1^2 + \cdots + x_n^2)^{q-j} \sum_{I \subset \{1, \dots, n\}, |I|=k} \left( \sum_{i \in I} x_i^2 \right)^j.$$

It is tempting to believe that  $c_2 = \dots = c_d = 0$  if this polynomial is rotation invariant. However, this is not true (not even for  $n = 2$ ) and this is precisely the reason why several cases have to be distinguished and additional geometric arguments are required.

If this is proved, then the invariance of  $K$  and  $f$  under  $\vartheta$  and the rotation covariance of  $\Gamma$  give

$$\Gamma(K, f)(\vartheta E) = \Gamma(\vartheta K, \vartheta f)(\vartheta E) = \Gamma(K, f)(E).$$

This is a contradiction, which finishes the proof of Theorem 5.1 for  $n \geq 4$ .

For  $n = 3$  and thus  $k = 1$  (and  $d$  odd) we work with a more flexible (depending on  $d$ ) triangular complex in  $\mathbb{R}^2$  and with Minkowski averages of the polytopes obtained by lifting the vertices of this complex.